

#### Description

The AZBDC12A8 PWM servo drive is designed to drive brushless and brushed DC motors at a high switching frequency. To increase system reliability and to reduce cabling costs, the drive is designed for direct integration into your PCB. The AZBDC12A8 is fully protected against over-voltage, over-current, overheating and short-circuits. A single digital output indicates operating status. The drive interfaces with digital controllers that have digital PWM output. The PWM IN duty cycle determines the output current and DIR input determines the direction of rotation. This servo drive requires only a single unregulated isolated DC power supply, and is fully RoHS II (Reduction of Hazardous Substances) compliant.

See Part Numbering Information on last page of datasheet for additional ordering options.

Power Range	
Peak Current	12 A
Continuous Current	6 A
Supply Voltage	20 - 80 VDC



#### **Features**

- ▲ Four Quadrant Regenerative Operation
- ▲ Direct Board-to-Board Integration
- ▲ Lightweight
- High Switching Frequency
- ▲ High Performance Thermal Dissipation

- Differential Input Command
- Digital Fault Output Monitor
- Current Monitor Output
- Single Supply Operation
- ▲ Compact Size
- ▲ High Power Density

## HARDWARE PROTECTION

- Over-Voltage
- Over-Current
- Over-Temperature
- Short-circuit (phase-phase)
- Short-circuit (phase-ground)

#### INPUTS/OUTPUTS

- Digital Fault Output
- Digital Inhibit Input
- Analog Current Monitor
- Analog Command Input
- Analog Current Reference

# FEEDBACK SUPPORTED

Hall Sensors

## MODES OF OPERATION

Current

# COMMUTATION

Trapezoidal

## **MOTORS SUPPORTED**

- Three Phase (Brushless)
- Single Phase (Brushed, Voice Coil, Inductive Load)

#### **COMMAND SOURCE**

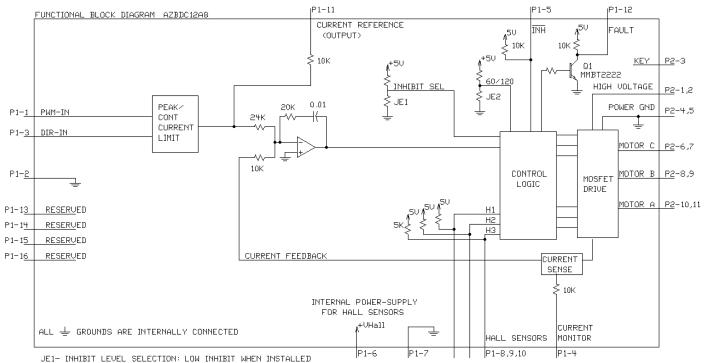
PWM

#### **COMPLIANCES & AGENCY APPROVALS**

- UL
- cUL
- CE Class A (LVD)
- CE Class A (EMC)
- RoHS II



#### **BLOCK DIAGRAM**



LOW ENABLE WHEN NOT INSTALLED

JE2- PHASING: 120 DEGREE WHEN INSTALLED, 60 DEGREE WHEN NOT INSTALLED

# US and Canadian safety compliance with UL 508c, the industrial standard for power conversion electronics. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products. Compliant with European EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007 for Emissions, Class A and EN 61000-6-2:2005 for Immunity, Performance Criteria A). LVD requirements of Directive 2006/95/EC (specifically, EN 60204-1:2004, a Low Voltage Directive to protect users from electrical shock). The RoHS II Directive 2011/65/EU restricts the use of certain substances including lead, mercury, cadmium, hexavalent chromium and halogenated flame retardants PBB and PBDE in electronic equipment.



# **SPECIFICATIONS**

Power Specifications			
Description	Units	Value	
DC Supply Voltage Range	VDC	20 - 80	
DC Bus Under Voltage Limit	VDC	18	
DC Bus Over Voltage Limit	VDC	88	
Maximum Peak Output Current <sup>1</sup>	А	12	
Maximum Continuous Output Current	Α	6	
Maximum Continuous Output Power	W	456	
Maximum Power Dissipation at Continuous Current	W	24	
Minimum Load Inductance (Line-To-Line) <sup>2</sup>	μH	100	
Internal Bus Capacitance <sup>3</sup>	μF	33	
Low Voltage Supply Outputs	-	+6 VDC (30 mA)	
Switching Frequency	kHz	31	
Control Specifications			

Control Specifications			
Description	Units	Value	
Command Sources	-	PWM	
PWM Input Frequency Range	kHz	10 - 25	
Feedback Supported	-	Halls	
Commutation Methods	-	Trapezoidal	
Modes of Operation	-	Current	
Motors Supported	-	Three Phase (Brushless), Single Phase (Brushed, Voice Coil, Inductive Load)	
Hardware Protection	-	Invalid Commutation Feedback, Over Current, Over Temperature, Over Voltage, Short Circuit (Phase-Phase & Phase-Ground)	

Mechanical Specifications			
Description	Units	Value	
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), cUL, RoHS II, UL	
Size (H x W x D)	mm (in)	63.5 x 50.8 x 16.8 (2.5 x 2 x 0.7)	
Weight	g (oz)	84.9 (3.0)	
Heatsink (Base) Temperature Range <sup>4</sup>	°C (°F)	0 - 75 (32 - 167)	
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)	
Form Factor	-	PCB Mounted	
P1 Connector	-	16-pin, 2.54 mm spaced header	
P2 Connector	-	11-pin, 2.54 mm spaced header	

# Notes

- 1. Maximum duration of peak current is ~2 seconds. Peak RMS value must not exceed continuous current rating of the drive.
- 2.
- Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements. Requires a  $100\mu F/100V$  electrolytic capacitor near the P2 Power Connector between High Voltage and Power Ground pins. 3.
- Additional cooling and/or heatsink may be required to achieve rated performance.



#### **PIN FUNCTIONS**

P1 - Signal Connector			
Pin	Name	Description / Notes	1/0
1	PWM / IN	10 – 25 kHz pulse width modulated digital input command (+5V). Input duty cycle commands the output current.	I
2	SIGNAL GND	Signal Ground	GND
3	DIRECTION	Direction Input (+5 V)	I
4	CURRENT MONITOR	Current Monitor. Analog output signal proportional to the actual current output. Scaling is 4 A/V. Measure relative to signal ground.	0
5	INHIBIT IN	TTL level (+5 V) inhibit/enable input. Leave open to enable drive. Pull to ground to inhibit drive. Inhibit turns off all power devices.	ı
6	+V HALL OUT	Low Power Supply For Hall Sensors (+6 V @ 30 mA). Referenced to signal ground. Short circuit protected.	0
7	SIGNAL GND	Signal Ground	GND
8	HALL 1		I
9	HALL 2*	Single-ended Hall/Commutation Sensor Inputs (+5 V logic level)	I
10	HALL 3		I
11	CURRENT REFERENCE	Measures the command signal to the internal current-loop. This pin has a maximum output of ±7.45 V when the drive outputs maximum peak current. Measure relative to signal ground.	0
12	FAULT OUT	TTL level (+5 V) output becomes high when power devices are disabled due to at least one of the following conditions: inhibit, invalid Hall state, output short circuit, over voltage, over temperature, power-up reset.	0
13	RESERVED		-
14	RESERVED	Reserved	-
15	RESERVED	Reserved	-
16	RESERVED		-

P2 - Power Connector			
Pin	Name	Description / Notes	1/0
1	HIGH VOLTAGE	DC Power Input. 3A Continuous Current Rating Per Pin. Requires a 100 $\mu$ F / 100 V	I
2	HIGH VOLTAGE	external electrolytic capacitor connected as close as possible to pins between High Voltage and Power Ground.	
3	NC (KEY)	Key: No Connection (pin removed)	-
4	PWR GND		GND
5	PWR GND	Power Ground (Common With Signal Ground). 3A Continuous Current Rating Per Pin	
6	MOTOR C		0
7	MOTOR C		0
8	MOTOR B	Motor Phase Outputs. Current output distributed equally across 2 pins per motor phase, 3A	0
9	MOTOR B	continuous current carrying capacity per pin.	0
10	MOTOR A		0
11	MOTOR A		

<sup>\*</sup>For use with Single Phase (Brushed) motors, ground Hall 2 and only connect motor leads to Motor A and Motor B.

# **HARDWARE SETTINGS**

# **Jumper Settings**

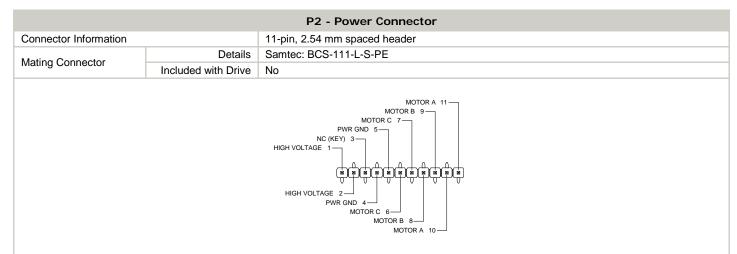
Jumpers are SMT, 0 ohm resistors located on the underside of the drive PCB. By default, the drive is configured with the jumpers installed. Typical drive operation will not require the jumpers to be removed. Please contact the factory before jumper removal.

Jumper	lumper Description		uration
	SMT Jumper ( $0\Omega$ Resistor)	Not Installed	Installed
JE1	Inhibit logic. Sets the logic level of inhibit pins. Labeled JE1 on the PCB of the drive.	Low Enable	Low Inhibit
JE2	Hall sensor phasing. Selects 120 or 60 degree commutation phasing. Labeled JE2 on the PCB of the drive.	60 degree	120 degree



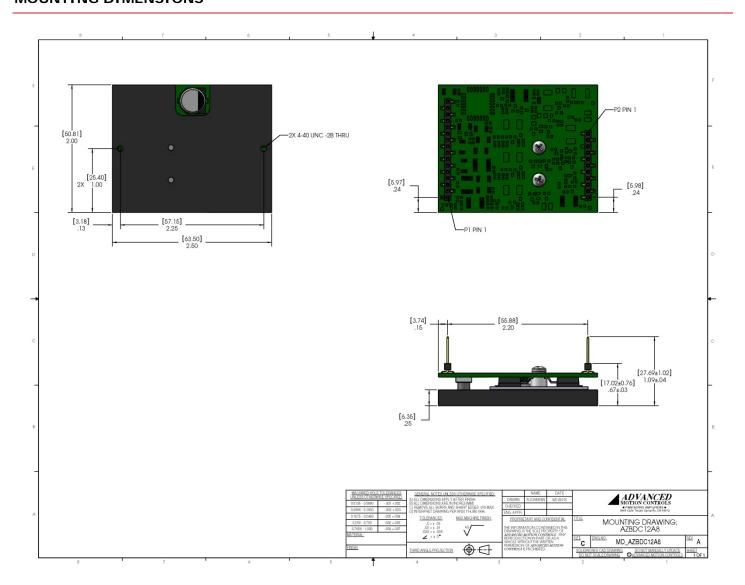
# **MECHANICAL INFORMATION**

P1 - Signal Connector				
Connector Information	Connector Information 16-pin, 2.54 mm spaced header			
Mating Connector	Details	Samtec: BCS-116-L-S-PE		
Mating Connector	Included with Drive	No		
11 CURRENT REFERENCE  9 HALL 2  7 SIGNAL GND  3 DIRECTION  1 PWM / IN  2 SIGNAL GND  4 CURRENT MONITOR  8 HALL 1  10 HALL 3  12 FAULT OUT				



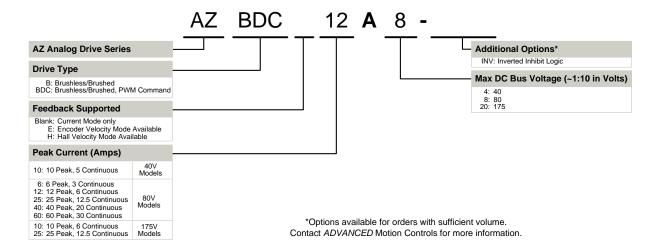


# MOUNTING DIMENSIONS





#### PART NUMBERING INFORMATION



ADVANCED Motion Controls AZ series of servo drives are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

#### **Examples of Modifications and Customized Products**

- Integration of Drive into Motor Housing
- Mount OEM PCB onto Drive Without Cables
- Multi-axis Configuration for Compact System
- Custom PCB and Baseplate for Optimized Footprint
- ▲ RTV/Epoxy Components for High Vibration
- OEM Specified Connectors for Instant Compatibility
- ▲ OEM Specified Silkscreen for Custom Appearance
- Increased Thermal Limits for High Temp. Operation
- Integrate OEM Circuitry onto Drive PCB
  - ▲ Custom Control Loop Tuned to Motor Characteristics
- Optimized Switching Frequency
- ▲ Ramped Velocity Command for Smooth Acceleration
- ▲ Remove Unused Features to Reduce OEM Cost
- ▲ Application Specific Current and Voltage Limits

Feel free to contact Applications Engineering for further information and details.

## **Available Accessories**

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit <a href="https://www.a-m-c.com">www.a-m-c.com</a> to see which accessories will assist with your application design and implementation.



All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.