

### Description

The DigiFlex® Performance™ (DP) Series digital servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The command source can be generated internally or can be supplied externally. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

This DP Series drive features an Ethernet interface for network communication using Ethernet POWERLINK, Modbus TCP or Ethernet, and a USB port for drive commissioning using DriveWare® 7, available for download at [www.a-m-c.com](http://www.a-m-c.com).

All drive and motor parameters are stored in non-volatile memory. The DPP Series Hardware Installation Manual is available for download at [www.a-m-c.com](http://www.a-m-c.com).

### Power Range

Peak Current	40 A (28.3 A <sub>RMS</sub> )
Continuous Current	20 A (20 A <sub>RMS</sub> )
Supply Voltage	100 - 240 VAC



ETHERNET  
**POWERLINK**

**Modbus**

**Ethernet**

### Features

- ▲ Four Quadrant Regenerative Operation
- ▲ Space Vector Modulation (SVM) Technology
- ▲ Fully Digital State-of-the-art Design
- ▲ Programmable Gain Settings
- ▲ Fully Configurable Current, Voltage, Velocity and Position Limits
- ▲ PIDF Velocity Loop
- ▲ PID + FF Position Loop
- ▲ Compact size, high power density
- ▲ 16-bit Analog to Digital Hardware
- ▲ Built-in brake/shunt regulator
- ▲ On-the-Fly Mode Switching
- ▲ On-the-Fly Gain Set Switching
- ▲ Dedicated Safe Torque Off (STO) Inputs

### MODES OF OPERATION

- Current
- Velocity
- Position

### COMMAND SOURCE

- ±10 V Analog
- Encoder Following
- Over the Network
- Sequencing
- Indexing
- Jogging

### FEEDBACK SUPPORTED (FIRMWARE DEPENDENT)

- Halls
- Incremental Encoder
- Absolute Encoder (EnDat® 2.1/2.2, Hiperface®, or BiSS C-Mode)
- 1Vp-p Sine/Cosine Encoder
- Auxiliary Incremental Encoder
- Tachometer (±10 VDC)

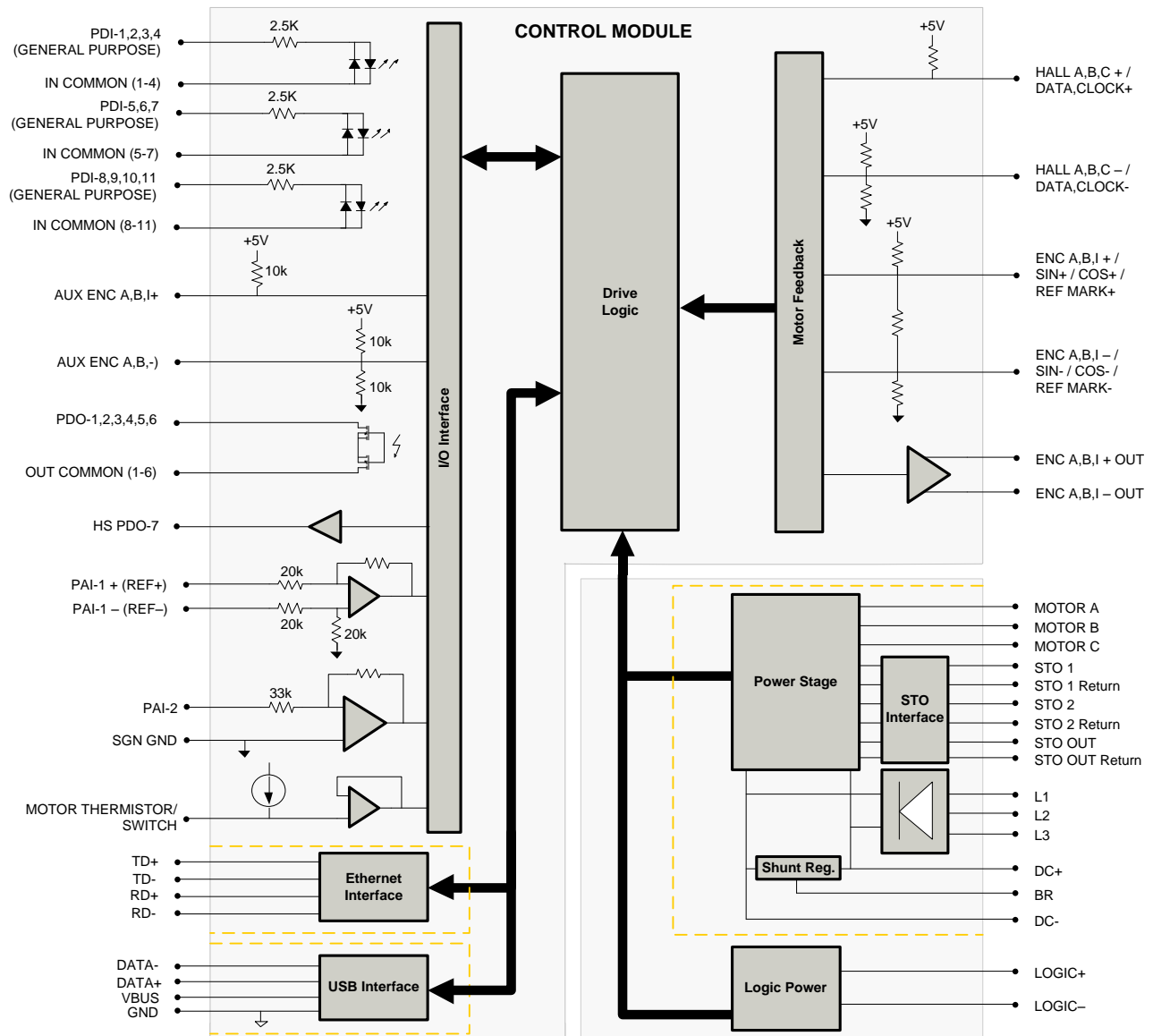
### INPUTS/OUTPUTS

- 1 Motor Thermistor/Switch Input
- 11 General Purpose Programmable Digital Inputs
- 1 High Speed Programmable Digital Output
- 6 General Purpose Programmable Digital Outputs
- 2 Programmable Analog Inputs

### COMPLIANCES & AGENCY APPROVALS

- CE Class A (LVD)
- CE Class A (EMC)
- RoHS II
- TÜV Rheinland® (STO)
- UL
- cUL

## BLOCK DIAGRAM



### Information on Approvals and Compliances



US and Canadian safety compliance with UL 508c, the industrial standard for power conversion electronics. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products.



Compliant with European EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007/A1:2011 for Emissions, Class A and EN 61000-6-2:2005 for Immunity, Performance Criteria A). LVD requirements of Directive 2006/95/EC (specifically, EN 60204-1:2006/A1:2009, a Low Voltage Directive to protect users from electrical shock).



The RoHS II Directive 2011/65/EU restricts the use of certain substances including lead, mercury, cadmium, hexavalent chromium and halogenated flame retardants PBB and PBDE in electronic equipment.



Functional Safety STO is TÜV Rheinland® certified and meets requirements of the following standards:

- EN ISO 13849-1 Category 4 / PL e
- EN IEC 61800-5-2 STO (SIL 3)
- EN62061 SIL CL3
- IEC 61508 SIL 3

## SPECIFICATIONS

Power Specifications		
Description	Units	Value
Rated Voltage	VAC (VDC)	240 (339)
AC Supply Voltage Range	VAC	100 – 240
AC Supply Minimum	VAC	90
AC Supply Maximum	VAC	264
AC Input Phases <sup>1</sup>	-	3
AC Supply Frequency	Hz	50 – 60
DC Supply Voltage Range <sup>2</sup>	VDC	127 – 373
DC Bus Over Voltage Limit	VDC	394
DC Bus Under Voltage Limit	VDC	55
Logic Supply Voltage	VDC	20 – 30 (@ 850 mA)
Safe Torque Off Voltage	VDC	24 (±6)
Maximum Peak Output Current <sup>3</sup>	A (A <sub>RMS</sub> )	40 (28.3)
Maximum Continuous Output Current <sup>4</sup>	A (A <sub>RMS</sub> )	20 (20)
Maximum Continuous Power @ Rated Voltage <sup>5</sup>	W	6441
Maximum Continuous Power Dissipation @ Rated Voltage	W	339
Internal Bus Capacitance	µF	660
External Shunt Resistor Minimum Resistance <sup>6</sup>	Ω	25
Minimum Load Inductance (Line-To-Line) <sup>7</sup>	µH	600
Switching Frequency	kHz	20
Maximum Output PWM Duty Cycle	%	100
Low Voltage Supply Outputs	-	+5 VDC (250 mA)
Control Specifications		
Description	Units	Value
Communication Interfaces	-	Ethernet POWERLINK / Modbus TCP / Ethernet (USB for Configuration)
Command Sources	-	±10 V Analog, Encoder Following, Over the Network, Sequencing, Indexing, Jogging
Feedback Supported	-	Halls, Incremental Encoder, Absolute Encoder (EnDat® 2.1/2.2, Hiperface®, or BiSS C-Mode), 1Vp-p Sine/Cosine Encoder, Auxiliary Incremental Encoder, Tachometer (±10 VDC)
Commutation Methods	-	Sinusoidal, Trapezoidal
Modes of Operation	-	Current, Velocity, Position
Motors Supported	-	Closed Loop Vector, Single Phase (Brushed, Voice Coil, Inductive Load), Three Phase (Brushless)
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage
Programmable Digital Inputs/Outputs (PDIs/PDOs)	-	11/7
Programmable Analog Inputs/Outputs (PAIs/PAOs)	-	2/0
Primary I/O Logic Level	-	24 VDC
Current Loop Sample Time	µs	50
Velocity Loop Sample Time	µs	100
Position Loop Sample Time	µs	100
Maximum Sin/Cos Encoder Frequency	kHz	200
Maximum Sin/Cos Interpolation	-	2048 counts per sin/cos cycle
Internal Shunt Regulator	-	Yes
Internal Shunt Resistor	-	No
Mechanical Specifications		
Description	Units	Value
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), RoHS II, TÜV Rheinland® (STO), UL, cUL
Size (H x W x D)	mm (in)	177.50 x 133.53 x 49.20 (6.99 x 5.26 x 1.94)
Weight	g (oz)	1720 (60.7)
Heatsink (Base) Temperature Range <sup>8</sup>	°C (°F)	0 - 75 (32 - 167)
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)
Cooling System	-	Natural Convection
Form Factor	-	Panel Mount
AUX. COMM Connector	-	5-pin, Mini USB B Type port
COMM Connector	-	Shielded, dual RJ-45 socket with LEDs
FEEDBACK Connector	-	15-pin, high-density, female D-sub
AUX. ENCODER Connector	-	15-pin, high-density, male D-sub
I/O Connector	-	26-pin, high-density, female D-sub
+24V LOGIC Connector	-	2-port, 3.5 mm spaced insert connector
AC POWER Connector	-	4-port, 5.0 mm spaced, push-in front spring connection header
MOTOR POWER Connector	-	4-port, 5.0 mm spaced, push-in front spring connection header
DC POWER Connector	-	5-port, 5.0 mm spaced, push-in front spring connection header
STO Connector	-	8-port, 2.0 mm spaced, enclosed, friction lock header

### Notes

- Can operate on single-phase VAC if peak/cont. current ratings are reduced by at least 30%.
- Large inrush current may occur upon initial DC supply connection to DC Bus.
- Capable of supplying drive rated peak current for 2 seconds with 10 second foldback to continuous value. Longer times are possible with lower current limits.
- Continuous A<sub>RMS</sub> value attainable when RMS Charge-Based Limiting is used.
- P = (DC Rated Voltage) \* (Cont. RMS Current) \* 0.95
- ADVANCED Motion Controls recommends using an external fuse in series with the shunt resistor. A 3 amp motor delay fuse is typical.
- Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
- Additional cooling and/or heatsink are required to achieve rated continuous performance.

## PIN FUNCTIONS

COMM – Ethernet Communication Connector				
Pin	Name	Description / Notes		I/O
1	RD+	Receiver + (100Base-TX)		I
2	RD-	Receiver - (100Base-TX)		I
3	TD+	Transmitter + (100Base-TX)		O
4	RESERVED	-		-
5	RESERVED	-		-
6	TD-	Transmitter - (100Base-TX)		O
7	RESERVED	-		-
8	RESERVED	-		-
9	RESERVED	-		-

I/O – Signal Connector				
Pin	Name	Description / Notes		I/O
1	PDO-1	General Purpose Programmable Digital Output (120 mA maximum)		O
2	PDO-2	General Purpose Programmable Digital Output (120 mA maximum)		O
3	PDO-3	General Purpose Programmable Digital Output (120 mA maximum)		O
4	OUT COMMON	Digital Output Common (1-6)		OCOM
5	GROUND	Ground		GND
6	PDO-4	General Purpose Programmable Digital Output (120 mA maximum)		O
7	PDO-5	General Purpose Programmable Digital Output (120 mA maximum)		O
8	HS PDO-7	High Speed Programmable Digital Output		O
9	PDO-6	General Purpose Programmable Digital Output (120 mA maximum)		O
10	PDI-1	General Purpose Programmable Digital Input		I
11	PDI-2	General Purpose Programmable Digital Input		I
12	PDI-3	General Purpose Programmable Digital Input		I
13	PDI-4	General Purpose Programmable Digital Input		I
14	IN COMMON	Digital Input Common (1-4)		ICOM
15	IN COMMON	Digital Input Common (5-7)		ICOM
16	PDI-5	General Purpose Programmable Digital Input		I
17	PDI-6	General Purpose Programmable Digital Input		I
18	PDI-7	General Purpose Programmable Digital Input		I
19	PDI-8	General Purpose Programmable Digital Input		I
20	PDI-9	General Purpose Programmable Digital Input		I
21	PDI-10	General Purpose Programmable Digital Input		I
22	PDI-11	General Purpose Programmable Digital Input		I
23	IN COMMON	Digital Input Common (8-11)		ICOM
24	PAI-1+	General Purpose Differential Programmable Analog Input or Reference Signal Input (16-bit Resolution)		I
25	PAI-1-			I
26	GROUND	Ground		GND

FEEDBACK – Feedback Connector*					
Pin	Incremental Encoder	Absolute Encoder	1Vp-p Sin/Cos Encoder	Description / Notes	I/O
1	HALL A+	DATA-	HALL A+	Differential Hall A+ / Differential Data Line (BiSS: SLO-)	I
2	HALL B+	CLOCK+	HALL B+	Differential Hall B+ / Differential Clock Line (BiSS: MA+)	I
3	HALL C+	N/C	HALL C+	Differential Hall C+	I
4	ENC A+	SIN +	SIN +	Differential Encoder A / Differential Sine Input (Leave open for BiSS and EnDat 2.2)	I
5	ENC A-	SIN -	SIN -		I
6	ENC B+	COS +	COS +	Differential Encoder B / Differential Cosine Input (Leave open for BiSS and EnDat 2.2)	I
7	ENC B-	COS -	COS -		I
8	ENC I+	REF MARK+	REF MARK +	Differential Encoder Index / Differential Reference Mark (Leave open for BiSS and EnDat 2.2)	I
9	ENC I-	REF MARK-	REF MARK -		I
10	HALL A-	DATA+	HALL A-	Differential Hall A- / Differential Data Line (BiSS: SLO+)	I
11	HALL B-	CLOCK-	HALL B-	Differential Hall B- / Differential Clock Line (BiSS: MA-)	I
12	SGND	SGND	SGND	5V Return (Signal Ground)	SGND
13	+5V OUT	+5V OUT	+5V OUT	+5V Encoder Supply Output. Short-circuit protected. (250mA)	O
14	THERMISTOR	THERMISTOR	THERMISTOR	Motor Thermal Protection	I
15	HALL C-	N/C	HALL C-	Differential Hall C-	I

\*Note: Feedback supported (Incremental Encoder, Absolute Sin/Cos Encoder, or 1Vp-p Sin/Cos Encoder) will be dependent on firmware.

**AUX. ENCODER – Auxiliary Encoder Connector**

Pin	Name	Description / Notes	I/O
1	ENC A+ OUT / RESERVED	Buffered Encoder Channel A Output* or Reserved.	O
2	ENC A- OUT / RESERVED		O
3	ENC B+ OUT / RESERVED	Buffered Encoder Channel B Output* or Reserved.	O
4	AUX ENC A+		I
5	AUX ENC A-	Auxiliary Encoder Input (For single ended signal leave negative terminal open)	I
6	AUX ENC B+		I
7	AUX ENC B-	Auxiliary Encoder Input (For single ended signal leave negative terminal open)	I
8	AUX ENC I+		I
9	AUX ENC I-	Auxiliary Encoder Index Input (For single ended signal leave negative terminal open)	I
10	ENC B- OUT / RESERVED		O
11	ENC I+ OUT / RESERVED	Buffered Encoder Index Output* or Reserved.	O
12	SGND	Signal Ground	SGND
13	+5V OUT	+5 VDC User Supply	O
14	PAI-2	Programmable Analog Input (12-bit Resolution)	I
15	ENC I- OUT / RESERVED	Buffered Encoder Index Output* or Reserved.	O

\*Buffered encoder output only available with incremental encoder or 1Vp-p sin/cos encoder feedbacks. 1:1 input-to-output ratio, 5V square wave output. Reserved pins for all other feedbacks.

**AUX. COMM - USB Communication Connector**

Pin	Name	Description / Notes	I/O
1	VBUS	Supply Voltage	O
2	DATA -	Data -	I/O
3	DATA +	Data +	I/O
4	RESERVED	-	-
5	USB GND	USB Ground	UGND

**Motor Power Connector**

Pin	Name	Description / Notes	I/O
1	CHASSIS	Chassis Ground	CGND
2	MOTOR A	Motor Phase A	O
3	MOTOR B	Motor Phase B	O
4	MOTOR C	Motor Phase C	O

**DC Power Connector**

Pin	Name	Description / Notes	I/O
1	DC-	Power Ground	PGND
2	NC	No Connect	-
3	DC+	DC Power Input	I
4	DC+	External Shunt Resistor Connection. Connect resistor between DC+ and BR.	-
5	BR		-

**AC Power Connector**

Pin	Name	Description / Notes	I/O
1	L1	AC Supply Input (Three Phase). External 20 A time delay fuses are recommended in series with the AC input lines.	I
2	L2		I
3	L3		I
4	CHASSIS	Chassis Ground	CGND

**+24V LOGIC - Logic Power Connector**

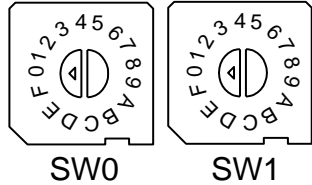
Pin	Name	Description / Notes	I/O
1	LOGIC GND	Logic Supply Ground	GND
2	LOGIC PWR	Logic Supply Input	I

**STO – Safe Torque Off Connector**

Pin	Name	Description / Notes	I/O
1	STO OUTPUT	Safe Torque Off Output	O
2	RESERVED	Reserved	-
3	STO-1 RETURN	Safe Torque Off 1 Return	STORET1
4	STO-1	Safe Torque Off – Input 1	I
5	STO-2 RETURN	Safe Torque Off 2 Return	STORET2
6	STO-2	Safe Torque Off – Input 2	I
7	RESERVED	Reserved	-
8	STO OUT RETURN	Safe Torque Off Output Return	STORETO

## HARDWARE SETTINGS

### Network IP Address Switches

Switch Diagram	Description																								
 <p>SW0 SW1</p>	<p>Hexadecimal switch settings correspond to the last octet of the IP Address of the drive within the Ethernet network. Note that for POWERLINK, the IP address will always be 192.168.100.xxx.</p> <table><tr><th>SW1</th><th>SW0</th><th>Node ID</th></tr><tr><td>0</td><td>0</td><td>Address stored in NVM</td></tr><tr><td>0</td><td>1</td><td>001</td></tr><tr><td>0</td><td>2</td><td>002</td></tr><tr><td>...</td><td>...</td><td>...</td></tr><tr><td>F</td><td>D</td><td>253</td></tr><tr><td>F</td><td>E</td><td>254</td></tr><tr><td>F</td><td>F</td><td>255</td></tr></table>	SW1	SW0	Node ID	0	0	Address stored in NVM	0	1	001	0	2	002	...	...	...	F	D	253	F	E	254	F	F	255
SW1	SW0	Node ID																							
0	0	Address stored in NVM																							
0	1	001																							
0	2	002																							
...	...	...																							
F	D	253																							
F	E	254																							
F	F	255																							

### LED Functions (on RJ-45 Communication Connectors)

LINK LED	
LED State	Description
Green – On	Valid Link - No Activity
Green – Flickering	Valid Link - Network Activity
Off	Invalid Link

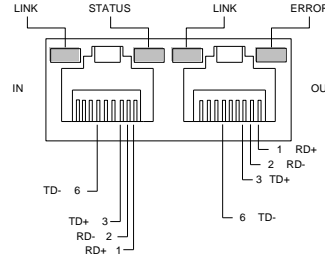
### Safe Torque Off (STO) Inputs

The Safe Torque Off (STO) Inputs are dedicated +24VDC max sinking single-ended inputs. A dedicated STO Disable Key connector is included and should be installed for applications where STO is not required.

## MECHANICAL INFORMATION

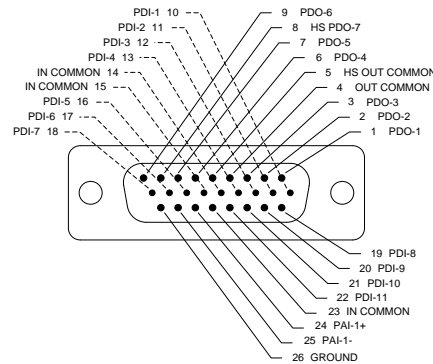
### COMM - Ethernet Communication Connector

Connector Information		Shielded, dual RJ-45 socket with LEDs
Mating Connector	Details	Standard CAT 5e or CAT 6 ethernet cable
	Included with Drive	No



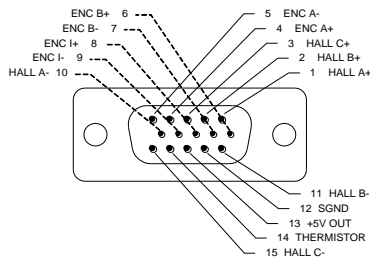
### I/O - Signal Connector

Connector Information		26-pin, high-density, female D-sub
Mating Connector	Details	TYCO: Plug P/N 1658671-1; Housing P/N 5748677-3; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)
	Included with Drive	No

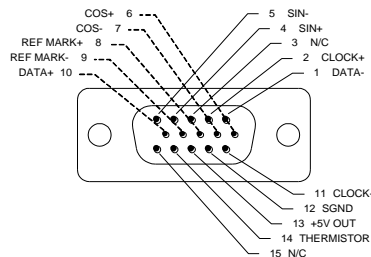


### FEEDBACK - Feedback Connector

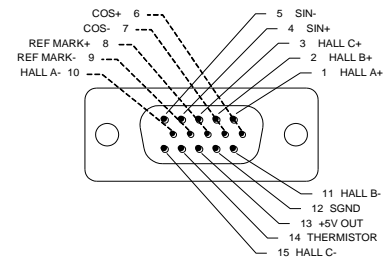
Connector Information		15-pin, high-density, female D-sub
Mating Connector	Details	TYCO: Plug P/N 748364-1; Housing P/N 5748677-2; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)
	Included with Drive	No



**Incremental Encoder**



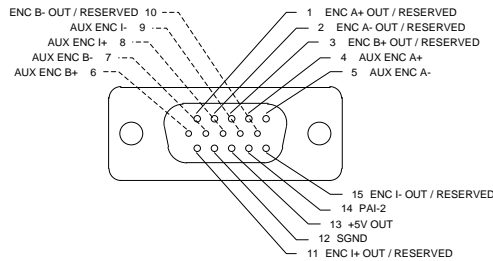
**Absolute Encoder**



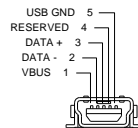
**1Vp-p Sin/Cos Encoder**

**AUX. ENCODER - Auxiliary Feedback Connector**

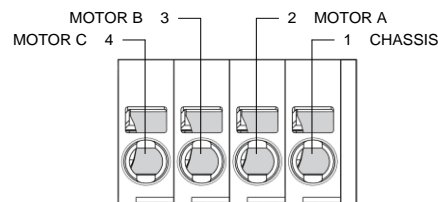
Connector Information		15-pin, high-density, male D-sub
Mating Connector	Details	TYCO: Plug P/N 1658681-1; Housing P/N 5748677-2; Terminals P/N 1658686-2 (loose) or 1658686-1 (strip)
	Included with Drive	No


**AUX. COMM – USB Communication Connector**

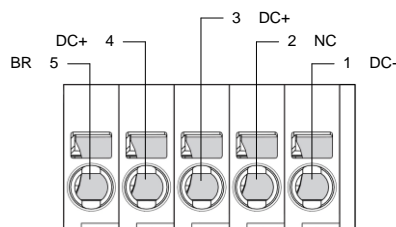
Connector Information		5-pin, Mini USB B Type port
Suggested Mating Cable	Details	TYCO: 1496476-3 (2-meter STD-A to MINI-B ASSY)
	Included with Drive	No


**Motor Power Connector**

Connector Information		4-port, 5.0 mm spaced, push-in front spring connection header
Mating Connector	Details	Push-in direct plug-in method for solid or stranded conductors with or without ferrules
	Included with Drive	No


**DC Power Connector**

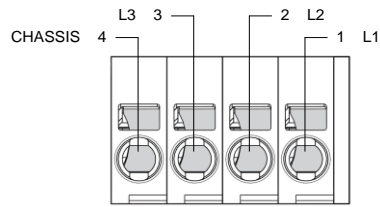
Connector Information		5-port, 5.0 mm spaced, push-in front spring connection header
Mating Connector	Details	Push-in direct plug-in method for solid or stranded conductors with or without ferrules
	Included with Drive	No





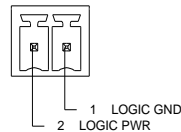
### AC Power Connector

Connector Information		4-port, 5.0 mm spaced, push-in front spring connection header
Mating Connector	Details	Push-in direct plug-in method for solid or stranded conductors with or without ferrules
	Included with Drive	No



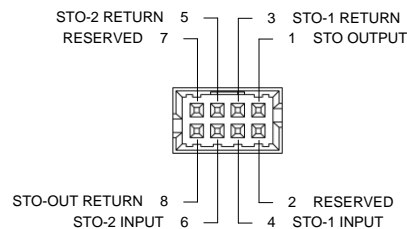
### +24V LOGIC - Logic Power Connector

Connector Information		2-port, 3.5 mm spaced insert connector
Mating Connector	Details	Phoenix Contact: P/N 1840366
	Included with Drive	Yes

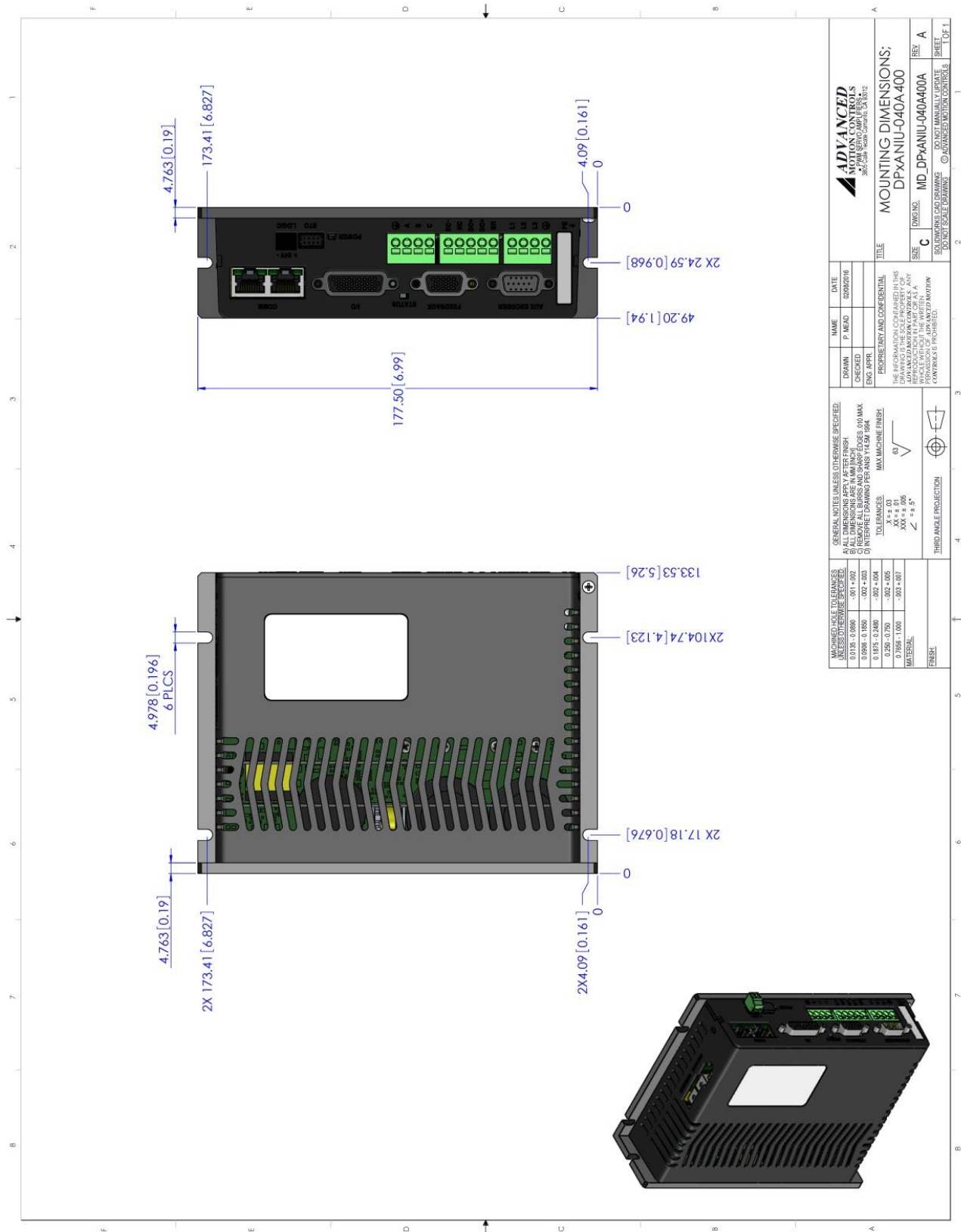


### STO – Safe Torque Off Connector

Connector Information		8-port, 2.00 mm spaced, enclosed, friction lock header
Mating Connector	Details	Molex: P/N 51110-0860 (housing); 50394-8051 (pins)
	Included with Drive	Yes

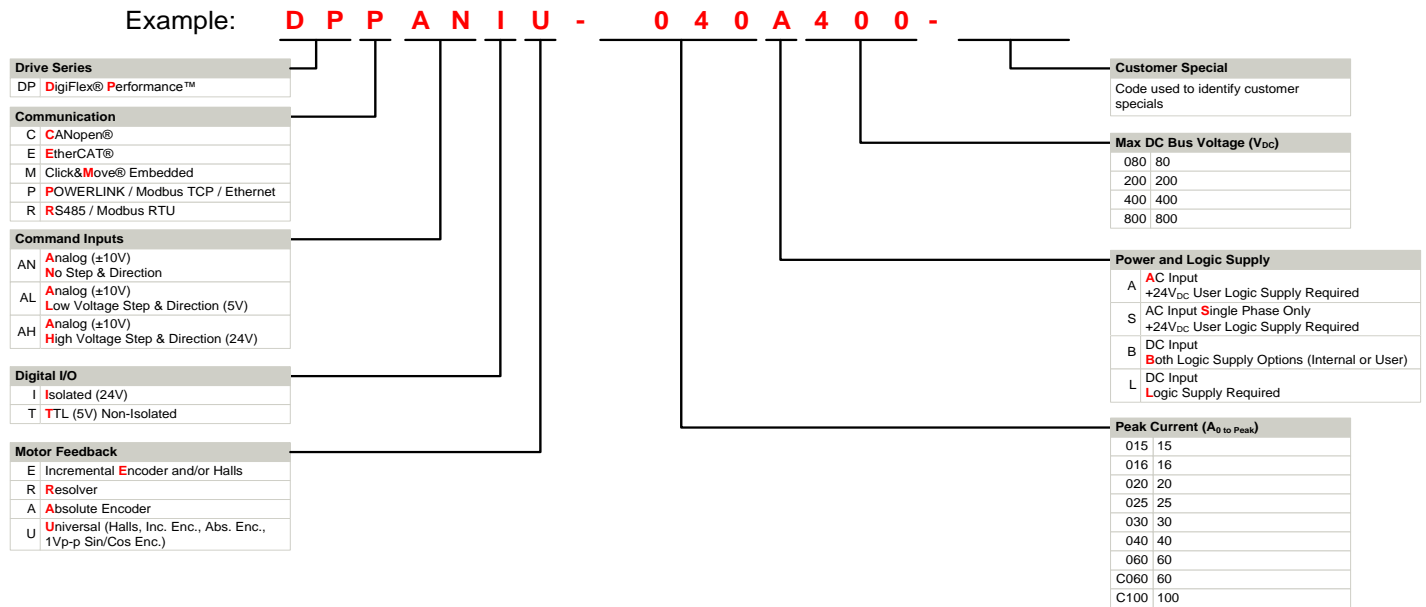


**MOUNTING DIMENSIONS**



<b>ADVANCED</b> MOTION CONTROLS 3805 Calle Tecate, Camarillo, CA 93012		NAME	DATE
		P. MEAD	02/06/2018
		DRAWN	
		CHECKED	
		ENG. APPR.	
		GENERAL NOTES UNLESS OTHERWISE SPECIFIED: A) ALL DIMENSIONS ARE IN INCHES UNLESS NOTED OTHERWISE. B) ALL DIMENSIONS ARE IN MILLIMETERS UNLESS NOTED OTHERWISE. C) INTERPRET DRAWING PER ANSI Y14.5M 1994.	
		PROPRIETARY AND CONFIDENTIAL THE INFORMATION CONTAINED IN THIS DRAWING IS THE SOLE PROPERTY OF ADVANCED MOTION CONTROLS. ANY REPRODUCTION IN PART OR AS A WHOLE WITHOUT THE WRITTEN PERMISSION OF ADVANCED MOTION CONTROLS IS PROHIBITED.	
		TOLERANCES: AS = ± .01 XX = ± .005 XXX = ± .002 4X = ± .005	
		FINISH: MAX MACHINE FINISH 8/1 3/16" ± .005 1/8" ± .005 1/4" ± .005 3/8" ± .005 1/2" ± .005 3/4" ± .005 1" ± .005 1 1/2" ± .005 2" ± .005 3" ± .005 4" ± .005 6" ± .005 8" ± .005 10" ± .005 12" ± .005 14" ± .005 16" ± .005 18" ± .005 20" ± .005 22" ± .005 24" ± .005 26" ± .005 28" ± .005 30" ± .005 32" ± .005 34" ± .005 36" ± .005 38" ± .005 40" ± .005 42" ± .005 44" ± .005 46" ± .005 48" ± .005 50" ± .005 52" ± .005 54" ± .005 56" ± .005 58" ± .005 60" ± .005 62" ± .005 64" ± .005 66" ± .005 68" ± .005 70" ± .005 72" ± .005 74" ± .005 76" ± .005 78" ± .005 80" ± .005 82" ± .005 84" ± .005 86" ± .005 88" ± .005 90" ± .005 92" ± .005 94" ± .005 96" ± .005 98" ± .005 100" ± .005	
		THIRD ANGLE PROJECTION	
		TITLE MOUNTING DIMENSIONS; DPPANIU-040A400	
		SIZE C	
		DWG NO. MD_DPPANIU-040A400A	
		REV. A	
		SHEET 1 OF 1	

## PART NUMBERING INFORMATION



DigiFlex® Performance™ series of products are available in many configurations. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability. Feel free to contact Applications Engineering for further information and details.

### Examples of Customized Products

- ▲ Optimized Footprint
- ▲ Private Label Software
- ▲ OEM Specified Connectors
- ▲ No Outer Case
- ▲ Increased Current Resolution
- ▲ Increased Temperature Range
- ▲ Custom Control Interface
- ▲ Integrated System I/O
- ▲ Tailored Project File
- ▲ Silkscreen Branding
- ▲ Optimized Base Plate
- ▲ Increased Current Limits
- ▲ Increased Voltage Range
- ▲ Conformal Coating
- ▲ Multi-Axis Configurations
- ▲ Reduced Profile Size and Weight

### Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit [www.a-m-c.com](http://www.a-m-c.com) to see which accessories will assist with your application design and implementation.



All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.